# **Photon Map Tricks**

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SIGGRAPH Course #38, 2001

#### Contents

- Six "tricks" to make the photon map method faster, better, and easier to use
- Some tricks give up to 10x improvement

#### Overview

- 1 "trick" for less flicker in animations
- 1 "trick" for improved ease of use
- 3 "tricks" for improved speed
- 1 "trick" for improved accuracy

## Trick #1: Less flickering animations

Frame-coherent random numbers

#### Goal

 When an object moves, only the photon paths directly influenced by the move should change



## Problem

- If one sequence of random numbers is used for reflection/refraction/absorption probabilities, then:
- If *one* photon path length changes, *all* the following photon paths will change, too!

#### Solution

- Several solutions; the simplest+best:
- Use a separate random number sequence for each photon. Seed can depend on just photon number
- Reduces flickering to ~ 1/10

### **Origins**

- Nuclear physics: Monte Carlo simulation of neutron scattering (1950s)
- References: [Goertzel58, Spanier69]

## Trick #2: Improved ease of use

Automatically computed maximum search radius for lookups

#### Background: radiance estimates

Two ways to determine photon density:

- Fixed number of photons (determine area)
- Fixed area (find all photons within area)



 $E = \Sigma P_n / A$ 

## Background: radiance estimates (2)

In practice, we use a combination of the two:

- Fixed number of photons in high and medium density regions
- Fixed area in sparse regions

Combination:

search for max n photons within max radius r

## Effects of the max search radius

- If the max radius is set too high: large parts of the kd-tree will be searched in sparse regions, only to result in a very dim radiance. Waste of time!
- If the max radius is set too small: the area either contains a photon or not. "Polka dot" pattern!

Optimal value: tedious trial-and-error

## Computing the max search radius

- Switch between number-limited and arealimited when the density is low enough that inaccuracies are not important:
  - $r = 1/\pi \sqrt{n P_{max} / Lt}$
  - n = number of photons
  - Pmax = max photon power
  - Lt = threshold radiance (e.g. 5% of white)

## Speedup

- Using an optimal max search radius is up to 10 times faster than using no max search radius (in sparse regions)
- This trick makes it trivial to find that optimal max radius

## Trick #3: Improved speed

Iterative lookups instead of recursive

#### Photon map lookup

- Find n photons closest to point p (within max radius r)
- Usually done with a recursive traversal of the kd-tree
- Normally trivial to rewrite recursive algorithm as iterative; faster

## Photon map lookup (2)

• BUT: the lookups have double recursion



• Question: is it nevertheless possible to rewrite as an iterative algorithm?

## Photon map lookup (3)

- Yes! (using two small auxiliary arrays)
- Algorithm is in course notes
- Speedup: up to 25%

## Trick #4: Improved speed

Final gathering using precomputed irradiance estimates

[Christensen00]: "Faster photon map global illumination", Journal of Graphics Tools, 4(3):1-10

#### **Observations**

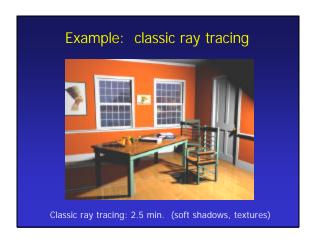
- 1. Final gathering is the bottleneck especially the photon map lookups
- 2. Rays from different final gathers hit nearly the same place: almost identical photon map lookups are repeated again and again

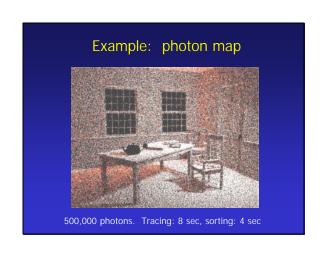
## Faster final gathering

- Precompute irradiance at all (or some) photon positions; store with photons
- During final gathering, use precomputed irradiance at the nearest photon with similar normal (Surf. are Voronoi diag.)

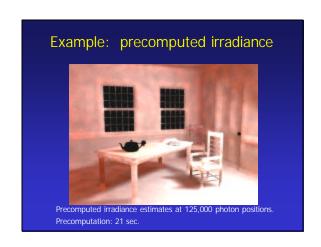
## Example

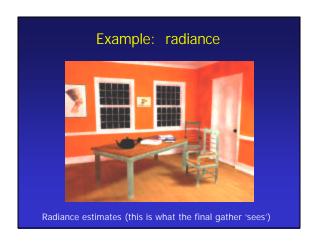
- >1M polygons
- 1024 x 768 pixels, up to 16 samples/pixel
- Linux PC with 733MHz Pentium, 540MB

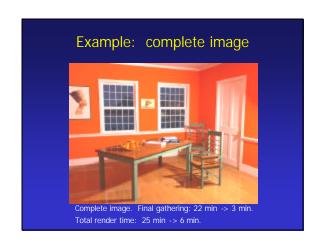












## Speedup

- Makes final gathering 5-8 times faster by removing the bottleneck
- Cost: precomputation time (<2%); extra memory (28%)

## Other applications

- Participating media: ray marching
- Importance ("importons" [Peter98])

#### **Variations**

- Compute irradiances "on demand" (instead of precomputation)
- Compute more than ¼ irradiances where there is high gradient in photon density
- Store radiance instead of irradiance:
  - saves many texture lookups
  - less accurate

#### More variations

- Other quantities can be stored with photons to save time
- See course notes

## Trick #5: Improved accuracy

Combining irradiance estimates from several photon maps

## Why have several photon maps?

- Usually not necessary
  - photon map fits within memory of one machine
  - Photon map can be shared among processors (shared memory)
- But in extreme cases several photon maps can be necessary (computed in parallel)

## Assumption

• Photons are evenly distributed among the photon maps

## Combining lookup results

 Each lookup produces a power Pm and a radius rm



· How to combine them?

## Combining lookup results (2)

- First idea: Etotal =  $\sum$  (Pm /  $\pi$  rm)
- Less statistical variation: combine powers and radii separately:

Etotal = 
$$(\Sigma Pm) / \pi ave(rm)^2$$

• Why better? Non-linear

## Trick #6: Improved speed

Photon tracing using importance

#### Goals

- 1. Reduce time to trace photons in very complex scenes
- 2. Reduce space, i.e # stored photons
- 3. No visible bias
- 4. No mixing of photons with high and low power in the photon map polka dots

## Importance strategy

- First: trace importance particles from the camera position [Peter98]
- During photon tracing: shoot few photons to unimportant regions

## Previous work using importance

- [Peter98]: reduced # traced and stored photons, but mixed low - and high-energy photons
- [Suykens00, Keller00]: reduced # stored photons, but not # traced photons

## Proposal: adaptive photon emission

- Divide directions from light source into small strata
- In each stratum: first send few "feeler" photons
  - if no feeler photon reach anything important: just store them in photon map
  - If some feeler photons reach something important: emit many more photons within that stratum

## Preliminary results

- Only 2 scenes
- Speedup: factor ~ 15
- No visible bias

#### To be done

- Experimental comparison with [Peter98]
  - bias
  - noise
- Extension to participating media

#### Conclusion

Six optimizations of the photon map method:

- Frame-coherent random numbers: reduce flicker to ~ 1/10
- Optimal r<sub>max</sub>: speedup ≤ 10
- Iterative lookup: speedup ≤ 25%

## Conclusion (2)

- Precomputing irradiance: speedup 5-8
- Improved combination of lookup results: higher accuracy (how much?)
- Photon tracing using importance: speedup ≤ 15

#### Future work

- Many more tricks to improve speed + accuracy await discovery ...
- · Let's find them!

## Acknowledgments

Many thanks to:

- Toshi Kato, Hitoshi Nishimura, Tadashi Endo, Tamotsu Maruyama, Jun Saito
- Everyone else at Square USA!

# Per Christensen

